



i-LEED

Advanced cattle feeding on pasture through innovative pasture management

- DELIVERABLE -

D4.4 Integration of the pasture robot in the i-LEED software

Due date of the deliverable: 1Q 2016

Released:

Responsible Partner: Effidence

Author(s): Tessier, Cédric
Charrette, Baptiste

Dissemination level

PU Public



REVISION HISTORY AND STATEMENT OF ORIGINALITY

Revision history:

Revision:	Date:	Author:	Organisation:	Description:
v.1.0	30.12.2016	Tessier, Cédric Charrette, Baptiste	Effidence	First draft, Formatting: new corporate project design template
	31.07.2017	Gobor, Zoltan	LfL	Proofreading, final approval

Statement of Originality:

This deliverable contains original unpublished work except where clearly indicated otherwise. Acknowledgement of previously published material and of the work of others has been made through appropriate citation, quotation or both.

The project **i-LEED** is funded within the frame of the 2nd call of the ICT-AGRI, which is a cross-thematic ERA-NET scheme of the 7th Framework Programme for Research and Technical Development.

D4.4 Integration of the pasture robot in the i-LEED software

Abstract

The whole system is described and presented in the following video. It summarizes each step of the deployment of a pasture robot:

- Learning of the scouting path with IRSTEA software,
- Scouting the pasture area with Effidence autonomous robot and doing grass analyzing and cowpats detection with Lfl technology,
- Collecting agricultural data in the DSP software
- Defining a path for maintenance operation with IRSTEA software
- Autonomous navigation with Effidence robot to do specific maintenance actions (mulching, seeding, spreading cowpats)

To see the video, please click on the picture below.



<https://www.youtube.com/watch?v=1-iqlac6VBw>